

EN



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# LRH 100.1

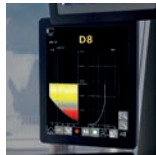
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LRH 3001.07  
[www.liebherr.com](http://www.liebherr.com)

## LIEBHERR

Piling rigs

# Concept and characteristics



**PDE**<sup>®</sup>  
Process Data Recording



**MyJobsite**



**LIPOS**<sup>®</sup>  
Positioning System



**LiDAT**<sup>®</sup>  
Data Transmission



## The robust universal machine

- Hydraulic hammer
- Pre-drill

## Assistance systems

- Joystick control for all machine functions
- Leader inclination memory
- Positioning system
- Free-fall winches with slack rope monitoring and prevention

# Technical description



## Diesel engine

|   |  |
|---|--|
| <b>Power rating according to ISO 9249</b> | 250 kW (335 hp) at 1700 rpm  |
| <b>Engine type</b>                        | Liebherr D 936 A7-04   |
| <b>Fuel tank capacity</b>                 | 700 l with continuous level indicator and reserve warning  |
| <b>Exhaust certification</b>              | EU 2016/1628 Stage V; EPA/CARB Tier 4f<br>ECE-R.96 Power Band H<br>non-certified emission standard |



## Hydraulic system

|                                     |  |
|-------------------------------------|--|
| <b>Pump for working tools</b>       | 2x 272 l/min   |
| <b>Separate pump for kinematics</b> | 130 l/min  |
| <b>Hydraulic oil tank capacity</b>  | 600 l  |
| <b>Max. working pressure</b>        | 350 bar  |
| <b>Hydraulic oil</b>                | electronic monitoring of all filters<br>use of synthetic environmentally friendly oil possible |



## Crawlers

|                            |  |
|----------------------------|--|
| <b>Drive system</b>        | with fixed axial piston hydraulic motors                       |
| <b>Crawler side frames</b> | maintenance-free, with hydraulic chain tensioning device       |
| <b>Brake</b>               | hydraulically released, spring-loaded multi-disc holding brake |
| <b>Drive speed</b>         | 0-2.0 km/h   |
| <b>Track force</b>         | 440 kN   |
| <b>Grousers</b>            | width 900 mm   |



## Swing gear

|                     |   |
|---------------------|---|
| <b>Drive system</b> | with fixed axial piston hydraulic motors, planetary gearbox, pinion |
| <b>Swing ring</b>   | roller bearing with external teeth                                  |
| <b>Brake</b>        | hydraulically released, spring-loaded multi-disc holding brake      |
| <b>Swing speed</b>  | 0-3.75 rpm continuously variable                                    |



## Hammer winch with free fall

|                              |            |
|------------------------------|------------|
| <b>Line pull (effective)</b> | 108 kN     |
| <b>Rope diameter</b>         | 24 mm      |
| <b>Rope speed</b>            | 0-66 m/min |



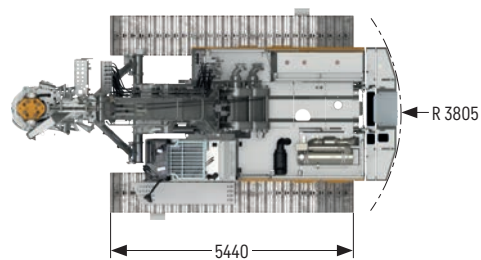
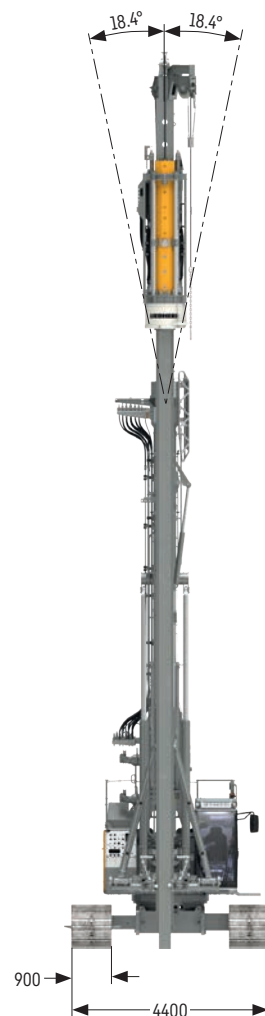
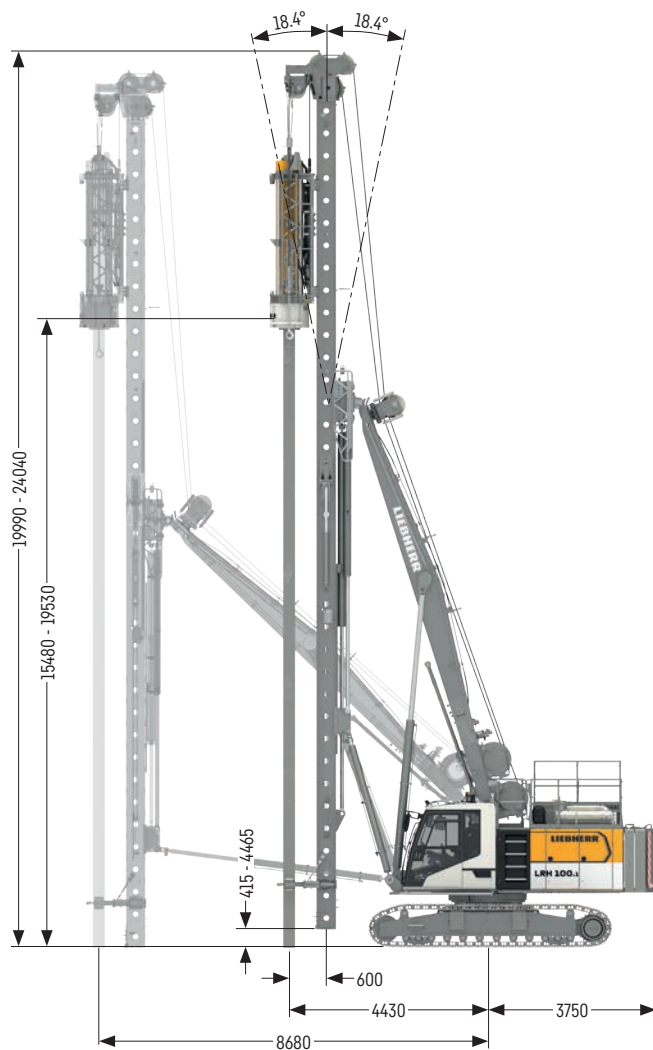
## Pile winch with free fall

|                              |            |
|------------------------------|------------|
| <b>Line pull (effective)</b> | 80 kN      |
| <b>Rope diameter</b>         | 20 mm      |
| <b>Rope speed</b>            | 0-66 m/min |

### Remarks:

- Illustrations showing the types of application (e.g. hydraulic hammer, pre-drill etc.) are examples only.
- Weights and transport dimensions can vary with the final configuration of the machine. The figures in this brochure may include options which are not within the standard scope of supply of the machine.

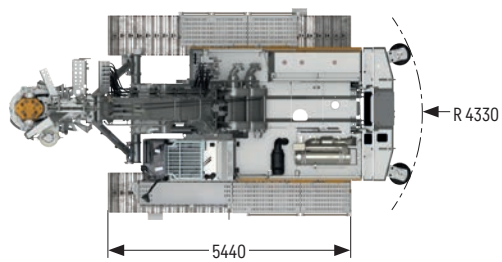
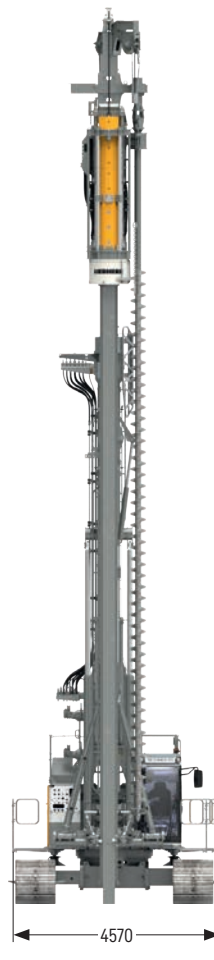
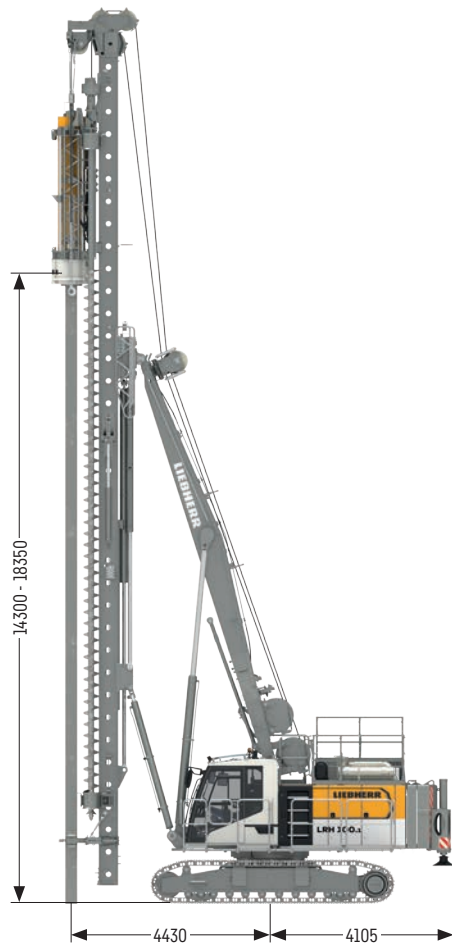
# Dimensions



## Operating weight

Total weight with 900 mm 3-web grousers t 71.3

The operating weight includes the basic machine LRH 100.1 incl. hammer H 6-6 and 13 t counterweight

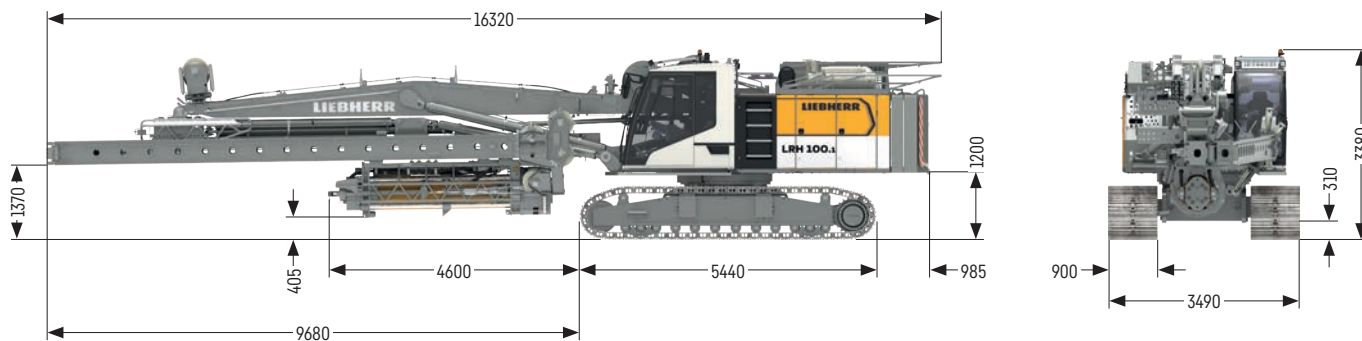


**Operating weight**

Total weight with 900 mm 3-web grousers t 72.2

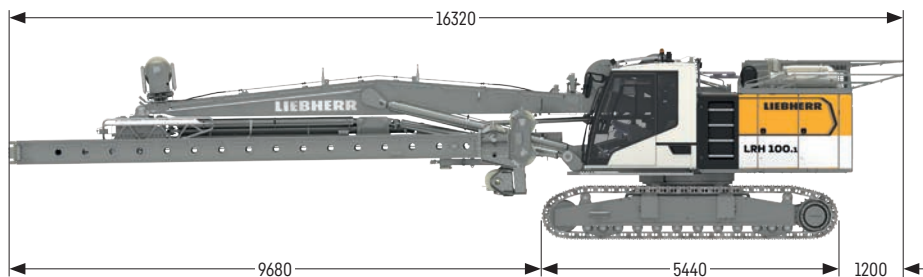
The operating weight includes the basic machine LRH 100.1 incl. hammer H 6-6, rotary BA 12 and 13 t counterweight.

# Transport dimensions and weights



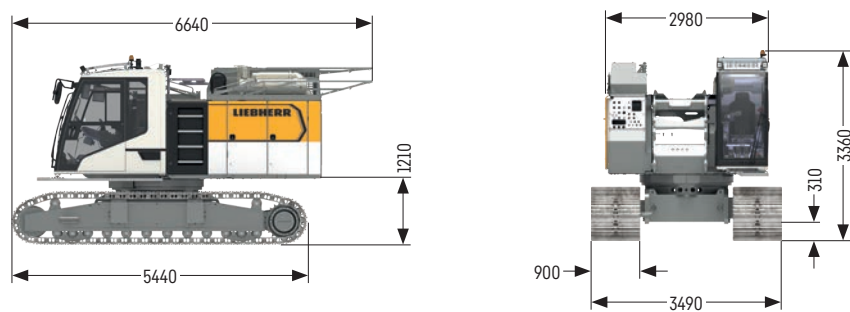
## Transport with hydraulic hammer

|  |        |
|--|--------|
| includes the basic machine (fully tanked and ready for operation) with leader, hydraulic hammer H 6-6 and 13 t counterweight | t 71.3 |
| Weight hydraulic hammer H 6-6  | t 9.6  |



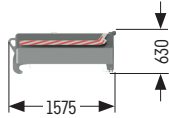
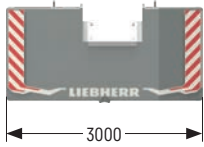
## Transport without hydraulic hammer

|   |        |
|---|--------|
| includes the basic machine (fully tanked and ready for operation) with leader, without hydraulic hammer and without counterweight | t 48.7 |
|---|--------|



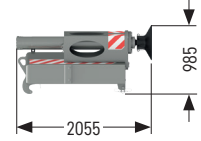
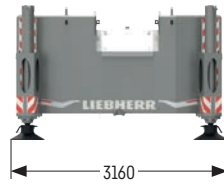
## Basic machine

|   |        |
|---|--------|
| fully tanked and ready for operation, without counterweight | t 31.1 |
|---|--------|



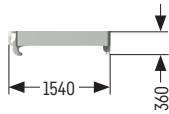
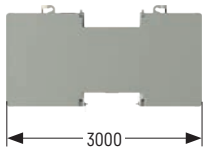
**Counterweight**

Weight t 8.0



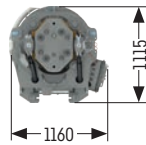
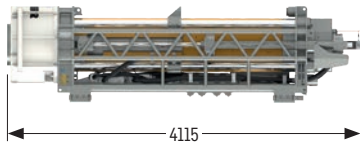
**Counterweight with rear support unit**

Weight t 8.0



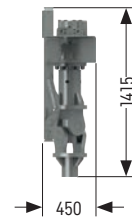
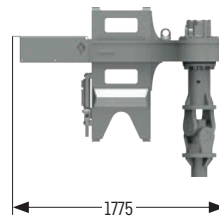
**Intermediate slab**

Weight t 5.0



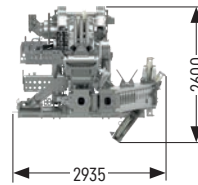
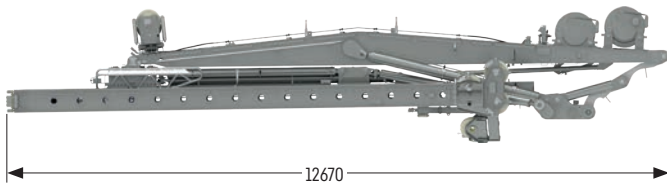
**H 6-6**

Weight incl. 6 t drop weight t 9.6



**BA 12**

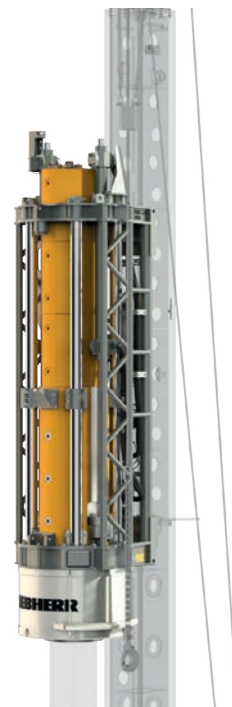
Weight t 0.62



**Leader**

Weight t 17.6

# Hydraulic hammer H 6



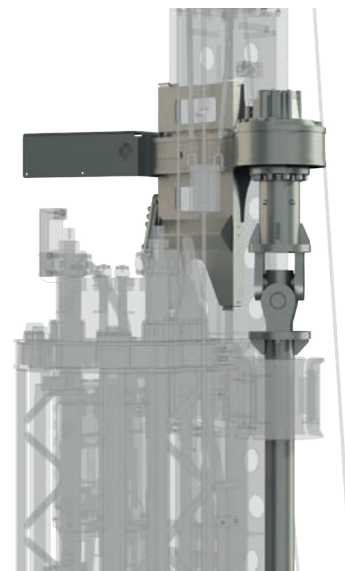
## Performance data

| Hammer type                               |           | H 6-3  | H 6-4  | H 6-5  | H 6-6  |
|---|-----------|--------|--------|--------|--------|
| Drop weight                               | kg        | 3000   | 4000   | 5000   | 6000   |
| Max. rated energy                         | kNm       | 36     | 48     | 60     | 72     |
| Blow rate                                 | blows/min | 50-150 | 50-150 | 50-150 | 40-150 |
| Max. pile length                          | m         | 19.5   | 19.5   | 19.5   | 19.5   |
| Hammer weight incl. pile helmet and dolly | kg        | 6600   | 7600   | 8600   | 9600   |

Various pile helmet sizes up to diameters of 630 mm or in square design available on request



# Pre-drill BA 12



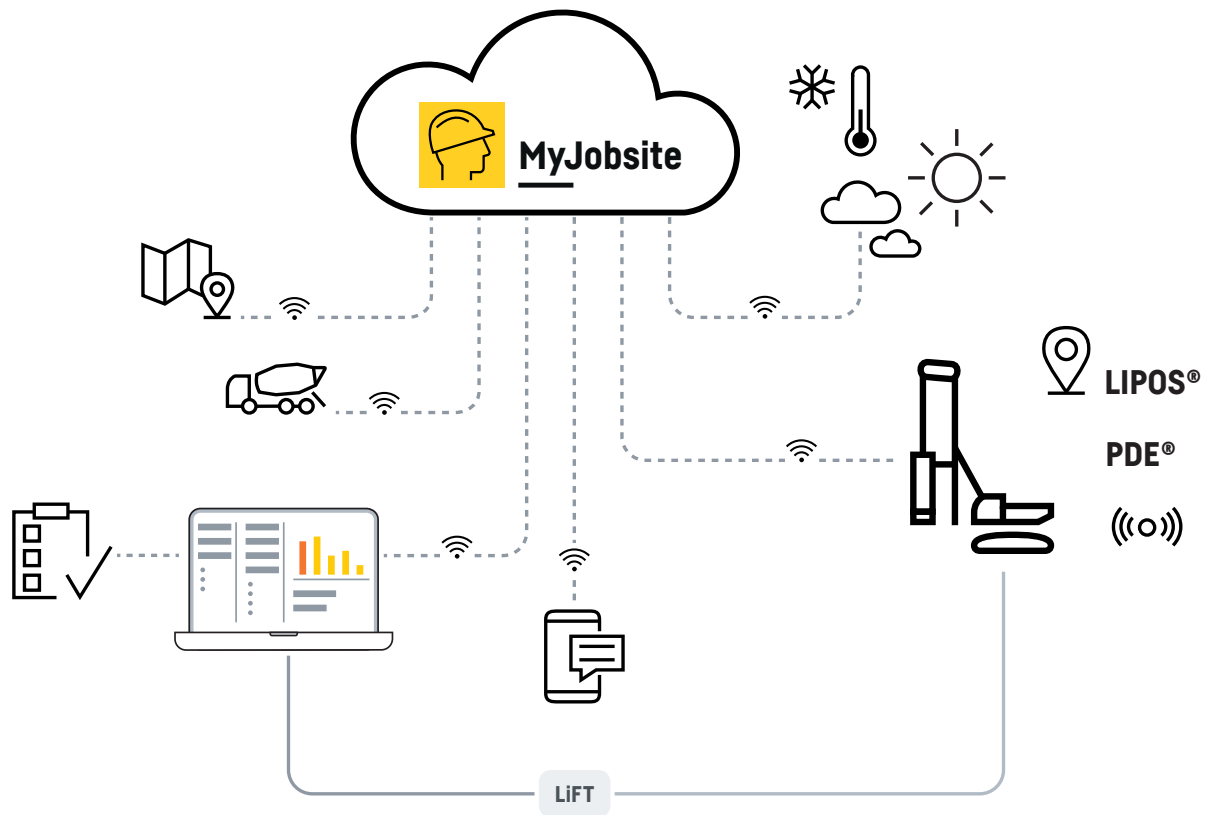
## Performance data

|                        |     |        |
|------------------------|-----|--------|
| Rotary drive - torque  | kNm | 12     |
| Rotary drive - speed   | rpm | 0 - 65 |
| Max. drilling diameter | mm  | 350    |
| Max. pile length       | m   | 18.3   |
| Max. drilling depth    | m   | 12     |

Other drilling diameters available on request

# Digitalization in deep foundation work

As deep foundation expert, Liebherr has created a combination of the most diverse assistance systems and software solutions in order to record and evaluate complex processes and to be able to provide the corresponding evidence.



## LIPOS – Liebherr Positioning System

Using pre-installed components, LIPOS enables the direct integration of machine control systems from Trimble and Leica. These systems are based on modern DGNSS technology (Differential Global Navigation Satellite System) and so achieve the best possible conditions for a precise and efficient positioning of Liebherr machines and their attachment tools.

## PDE

All working processes can be electronically recorded and visualized using the process data recording system PDE. The system is operated and displayed on the PDE touchscreen in the operator's cab. PDE records operating data from the Litronic control system, as well as data from external sensors.

## MyJobsite

Using the MyJobsite software solution all relevant process, machine, construction site and positioning data (LIPOS) can be recorded, displayed, analysed, managed

and evaluated in one central location. The collected data can be accessed via a web browser when an internet connection is active.

With the recorded PDE data, such as the driving progress of the pile per blow, the total number of blows, or the impact frequency per minute, a driving protocol is automatically generated as proof of quality directly after completion of a work process. The parameters of the driving protocol can be defined and assigned in advance. Using the templates saves a lot of time when creating the protocols.

MyJobsite is THE tool for quality control and documentation. The deluge of data, which is accrued each day from a wide variety of sources on the jobsite, can be recorded precisely and processed in an informative manner. Unpopular bureaucratic work is kept to a minimum and the amount of time required for it is significantly reduced. At the same time, the quality of administration work is maximised.





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